

Nr crt	Nr. matricol	Sisteme de achizitie si interfete														Med.an IV	K	Restante		
		Roboti mobili		Biomimetica sistemului locomotor		Actionarea sistemelor mecatronice		Dinamica robotilor		Sisteme robotizate de fabricatie si asamblare		Limba straina 2		Practica pt elaborarea proiectului de diploma 1					Elaborarea proiectului de diploma	
		C	F	C	F	C	F	C	F	C	F	C	F	C	F					F
3	6	3	6	4	4	2	2	5	2	4	6	5	2	2	4					
1	7465	0	7	5	7	0	8	7	10	0	7	7	5	5	7	9	adm	48	AM, SIM1, Grafica3, SIM2/RM1, RM2, OM1, Vibratii/OM2, Limba1, SSS, Practica spec-8	
2	8358	0	0	5	7	5	7	10	10	0	8	6	5	0	7	0	0	35	SIM1, Grafica1, Grafica3, Ed fiz1/Mecanisme, OM1, PAC, Vibratii, Practica dom/OM2, MF, Electroth, BSA, SA1, SSS	
3	7931	5	6	7	7	5	8	7	10	0	8	6	7	7	8	0	0	49	SIM1/-/-	
4	8379	0	0	0	0	5	8	6	0	0	7	5	5	0	6	0	0	24	SIM1, Mec1, Grafica1, SIM2/Mecanisme, Termoth2, OM1/OM2,MF, MUPA, BSA, SA1, SSS	
5	8707	6	9	7	7	0	0	8	0	6	0	6	6	5	10	0	adm	46	-/OM2-4/6, SSS-5, Practica spec-7	
6	7544	5	7	7	5	0	6	8	0	0	0	0	0	0	0	0	0	24	-/RM1, RM2, PAC/OM2, MM	
7	8426	8	9	10	9	8	10	9	10	7	8	8	6	6	10	10	adm	8,2321	60	0
8	8449	0	0	0	0	0	0	7	0	0	0	0	0	0	0	9	0	4	-/RM1, OM1, PAC/OM2, BSA, SA1, SSS, MM, Practica spec	
9	8454	7	8	7	8	5	9	10	10	7	8	10	7	7	9	10	adm	7,8571	60	SIM1-5/RM1-6, Mecanisme-5, Termoth2, TCD/OM2-6, SA1-5
10	8463	0	0	5	5	5	6	8	0	0	7	5	6	5	8	9	adm	44	SIM1, Mec2, Termoth1-5, Ed fiz1-adm/OM1, Tribologie-7, Vibratii-5/OM2, MF, MUPA, SA1, SSS	
11	8468	9	7	9	7	6	10	9	10	6	10	8	7	5	10	0	0	54	-/OM2-5	
12	8721	8	10	7	9	6	9	9	0	5	7	6	6	5	10	0	0	52	-/OM2-5	
13	8481	10	9	9	10	8	10	10	10	9	8	9	6	8	10	10	adm	8,8571	60	0
14	8490	8	8	6	9	5	7	8	10	0	0	0	0	0	0	9	adm	36	SIM1, Grafica1, Mec2, Grafica3/RM1, Termoth2/OM2, SA1, SSS	
15	8502	10	10	10	10	9	10	10	10	9	10	10	10	10	10	10	adm	9,8393	60	0
16	8507	8	7	8	7	5	10	9	10									55	SIM1, Grafica1, Mec2, Ed fiz1/Termoth2, Ed fiz2, Ed fiz3/OM2, SA1	
17	6870	7	8	0	6	8	9	10	0	5	6	8	6	5	10	0	0	49	Grafica2, Grafica3/ Mecanisme, PAC	
18	6876	7	6	0	6	5	9	7	0	0	0	0	5	7	7	0	0	38	Grafica2/RM1-6/OM2, SA1, Micromasini	
19	8538	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	-/Vibratii/OM2, SA1, SSS	
20	8729	10	9	10	10	9	10	10	10	7	8	10	9	9	9	10	adm	9,25	60	0
21	7668	6	8	6	6	6	9	10	0	0	8	8	6	7	10	10	adm	53	0	
22	8730	7	7	8	10	6	9	9	10	6	8	6	8	8	10	10	adm	7,9107	60	-/RM2-5, OM1-6/OM2-5, SSS, Practica spec - 8
23	8562	9	9	6	10	5	9	7	10	6	8	6	9	6	10	10	adm	7,9107	60	-/RM2-6, OM1-5/ -
24	8567	9	8	9	9	7	10	9	10	0	8	6	6	7	7	0	0	49	SIM1/ -/OM2	
25	8571	9	8	8	8	5	9	10	10	7	10	8	7	8	10	10	adm	8,0714	60	0
26	8579	10	9	10	9	7	10	10	10	7	10	10	10	10	10	10	adm	9,3036	60	0
27	8140	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	SIM1, Grafica1, Grafica2, Mecanica2, Grafica3/MN1, OM1, PAC/OM2, MF, MUPA, MN2, BR, SSS, Electronica	
28	8609	9	8	7	7	5	9	6	0	0	8	8	8	6	7	0	0	47	-/Vibratii-5/OM2-6, BSA-5	
29	8738	10	9	10	10	9	10	10	10	6	10	10	9	10	10	10	adm	9,3571	60	0
30	8620	7	6	7	8	5	10	9	9	6	8	8	6	6	10	9	adm	7,2143	60	Ed fiz1-adm(in cat)/RM1-5/OM2-8, Practica spec-7
31	8171	5	0	0	0	6	7	9	10	0	7	6	5	7	9	10	adm	40	-/MF, Electroth-7, MUPA, Limba1, SSS, MM, Micromasini	
32	6983	6	8	7	6	7	8	8	0	5	7	7	6	5	8	0	0	52	Grafica1, Grafica2,Algebra/RM1/OM2	
33	8191	6	6	5	6	5	7	7	0	4	10	9	6	8	8	10	adm	53	-/Practica spec	
34	8666	7	7	8	8	5	9	9	10	4	9	8	6	6	10	10	adm	55	0	
35	8677	9	8	8	8	5	10	9	10	6	10	9	8	7	10	10	adm	8,1071	60	-/OM2-5
36	8687	0	7	5	6	5	9	8	0	5	7	6	6	8	8	0	0	49	SIM1-5,Mec1, Grafica1-5, Mec2-5/Termoth2, OM1-5, Vibratii-5/OM2-5, MUPA,SA1-4, BR	
37	8695	7	6	5	10	5	9	8	10	8	9	9	7	7	6	9	adm	7,5893	60	Ed fiz1/ Mecanisme-5, Termoth2-5/OM2-5, BSA-5
38	8699	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Mec2, Termoth1/RM1, Mecanisme, Termoth2, RM2, PAC/OM2, MF, MUPA, BR, SSS, Electronica	
39	8267	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	AM,Grafica1,Termoth1/RM2,OM1,PAC,Practica dom/OM2, MUPA, BR, Biomecanica, Practica spec	
40	8704	6	7	6	8	5	9	9	10	0	8	8	7	5	10	9	adm	55	Ed fiz1/Mecanisme-5, Termoth2-5, RM2-6, OM1-6/OM2-6, BR-7	